

Application of Mean Recentering Scheme to  
Improve the Typhoon Track Forecast: A Case  
Study of Typhoon Nanmadol (2011)

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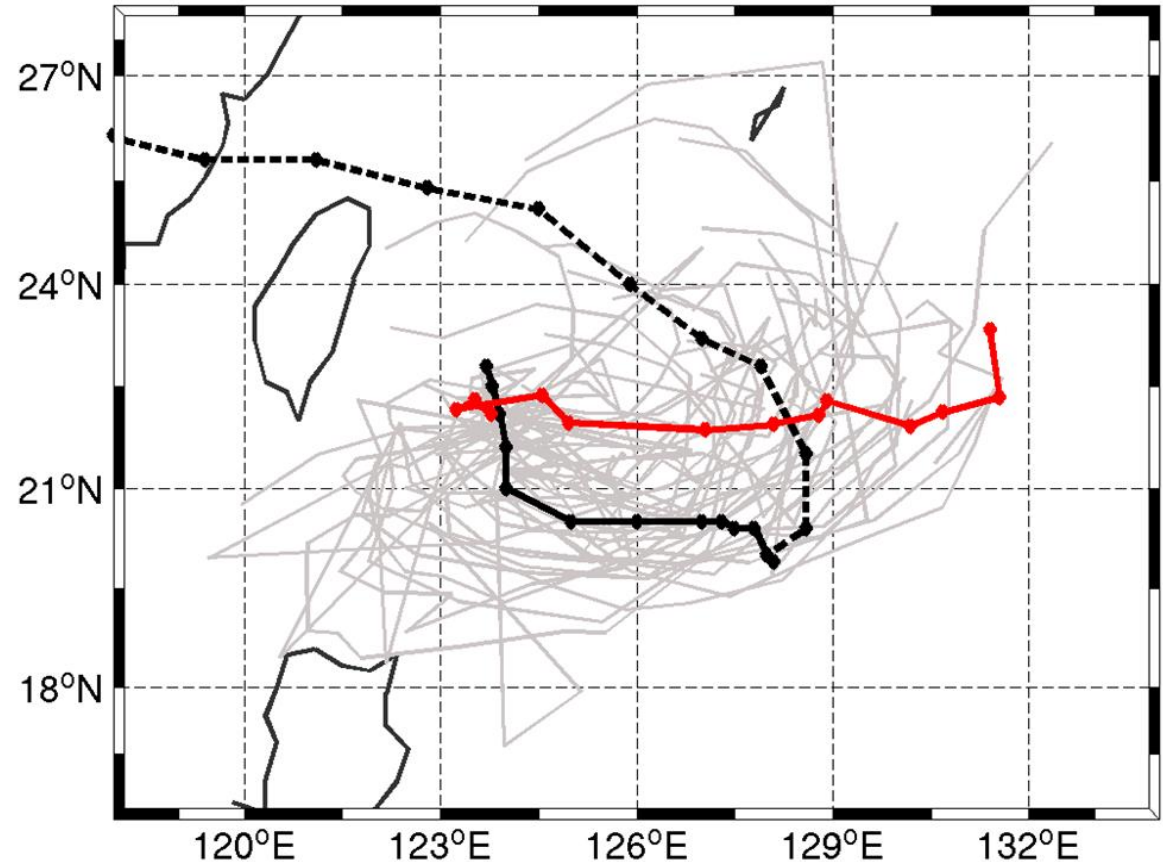
Christian Keppenne

NASA/GSFC, U.S.A

# Ensemble forecast for Trami (2013)

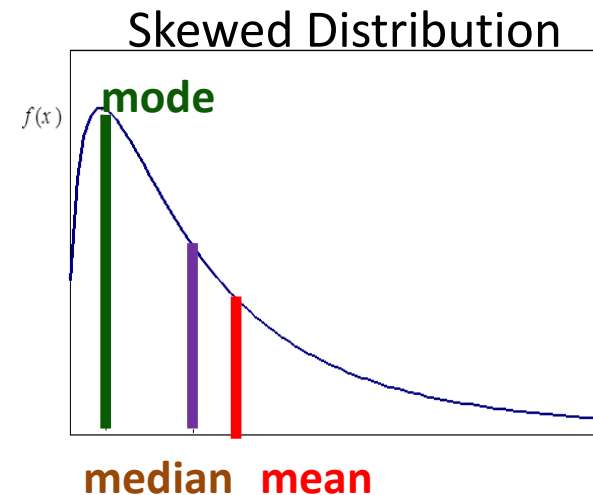
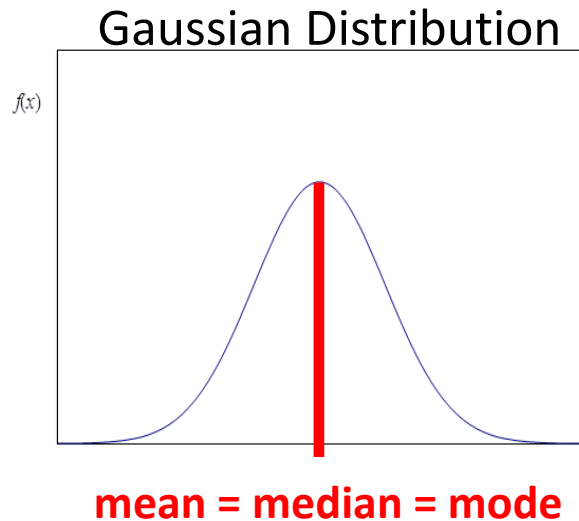
- **Cold-started** ensemble prediction system(EPS) with **36** members.
- I.C. comes from **WRF-based EPS**

Ensemble forecast initialized at 00z 16 Aug.



# Introduction

- If the ensemble is **normally distributed**, the mean state is the most likely state and can be used as the **optimal estimation** of the realistic state.
- However, if the ensemble **violates** the Gaussian distribution, the mean state **is not representative for the best estimate**.



# Introduction

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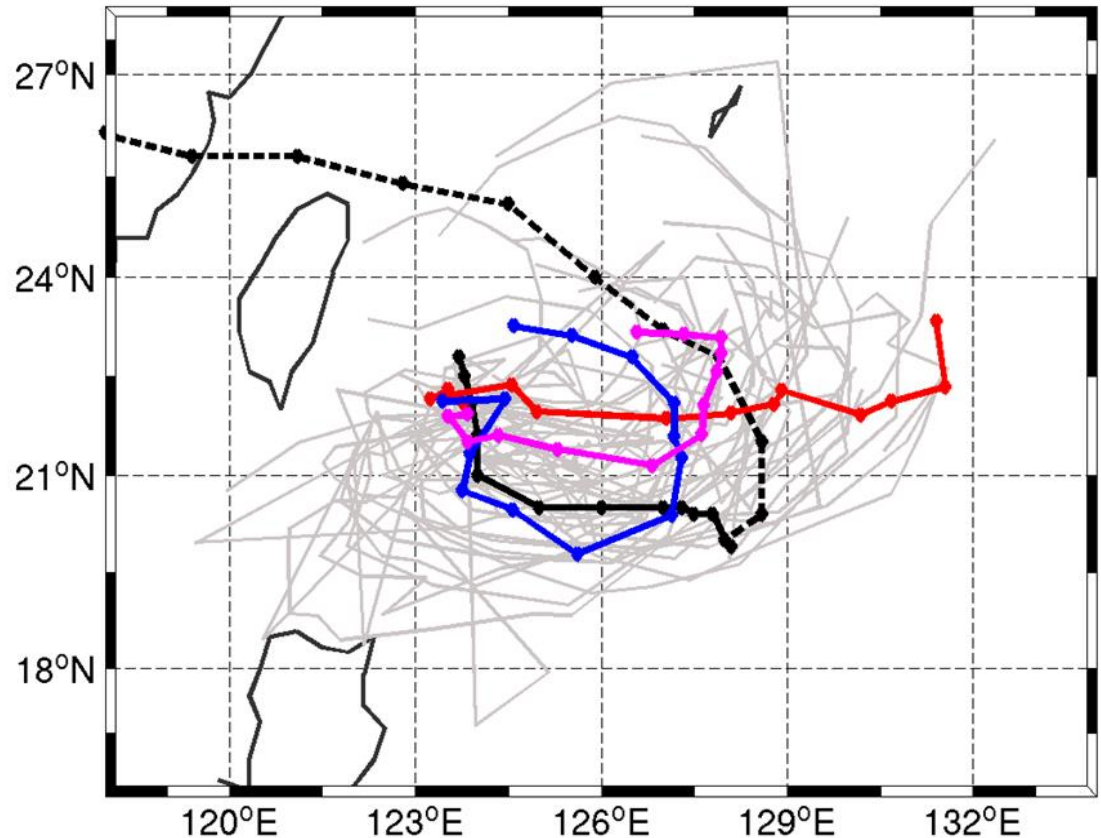
- With a poor ensemble, the ensemble mean cannot well represent the behavior of the realistic state, **BUT it is possible that some ensemble members can.**
- The purpose of **mean recentering scheme (MRC)** is to use those members to **'recenter'** the ensemble and aims to improve the nonlinear evolution of ensemble.
- MRC method is inspired by the ensemble recentering Kalman filter (**ERKF**) proposed by Keppenne (2013).

# Mean Recentering Scheme (MRC)

- CWB best track
- Ensemble mean
- Best member
- Ensemble mean with MRC

$$\mathbf{X}'_j = \mathbf{X}_j - \bar{\mathbf{x}},$$
$$\mathbf{X}_{\text{new}} = \mathbf{X}'_j + \mathbf{X}_{\text{best}}$$

Ensemble forecast initialized at 00z 16 Aug.

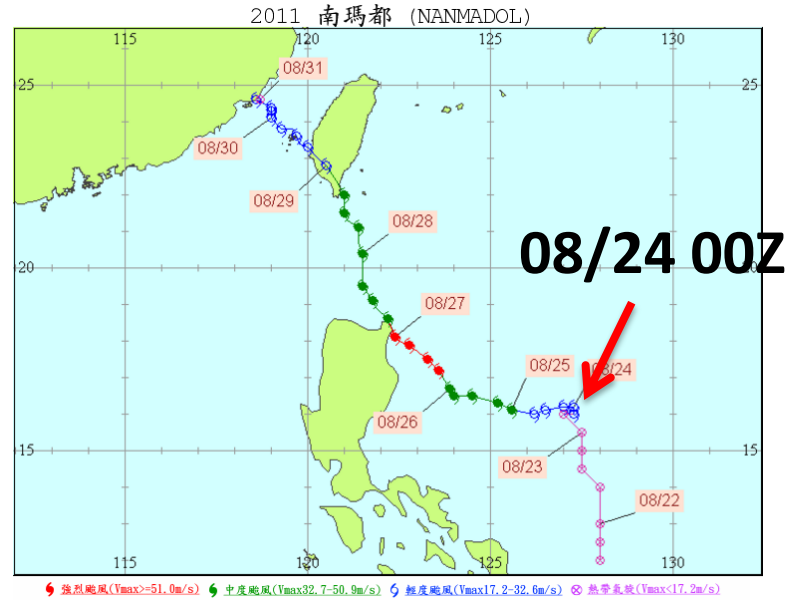


Best member selection is based on the accumulated track error

# Typhoon Nanmadol (2011)

EC global ensemble forecast from  
**TIGGE** (THORPEX Interactive Grand  
 Global Ensemble)

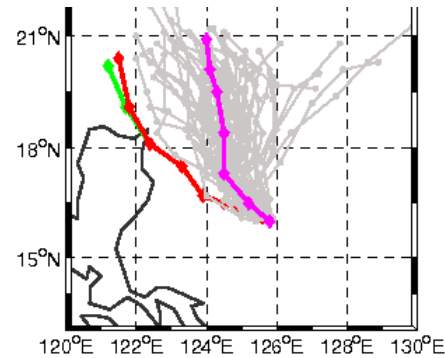
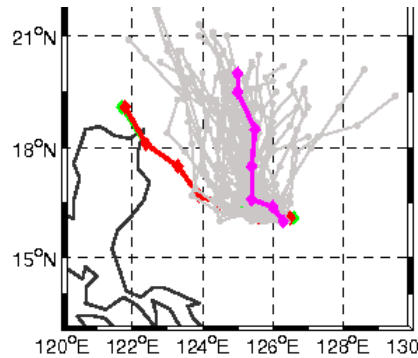
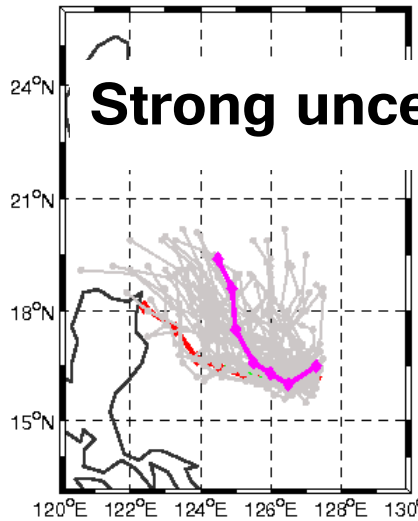
- Members (51)
- Mean forecast
- Analysis
- **CWB best track**



ECensemble\_2400

ECensemble\_2412

ECensemble\_2500



**Strong uncertainties at Nanmadol's early stage!!!**

# Experimental setting

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## Model Setup :

**WRF model v3.2.1** is used in this study and the simulation domain is **171\*141\*27** with **27 km** resolution.

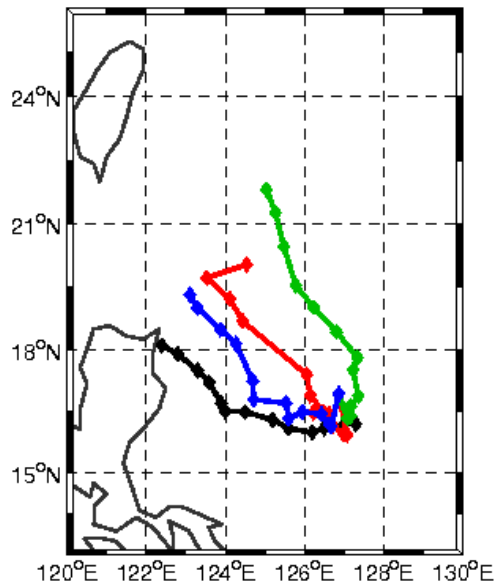
## Experiment design:

- A) **Ensemble Prediction System (cold-started EPS)** with MRC
- Ensemble: NCEP-AVN analysis + random perturbations (**36 members**)
  - **No feedback to next prediction**
- B) **Ensemble Data Assimilation System (warm-started EPS)** with MRC
- Data assimilation system: **WRF-LETKF** (Yang et al. 2014)
  - **Feedback to next prediction**

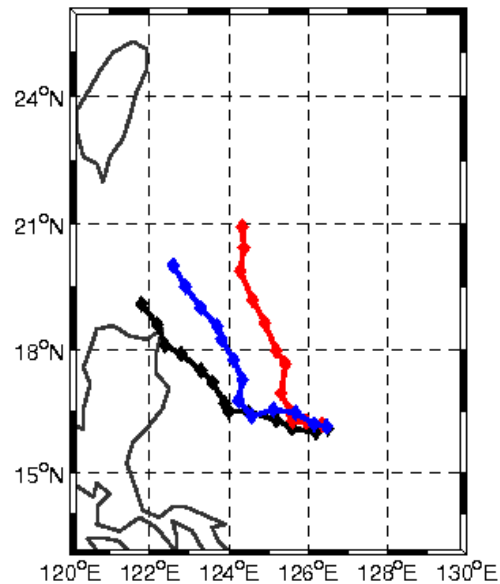
# Cold-started EPS

- CWB best track
- CNT: the control run (standard cold-started EPS)
- MRC\_12 : Use **12hr** accumulated track error to select best member
- MRC\_24: Use **24hr** accumulated track error to select best member.

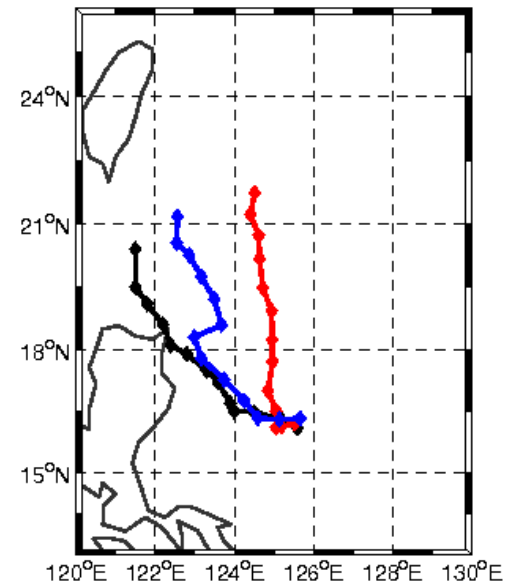
Initialized at 00Z 24 Aug.



Initialized at 12Z 24 Aug.

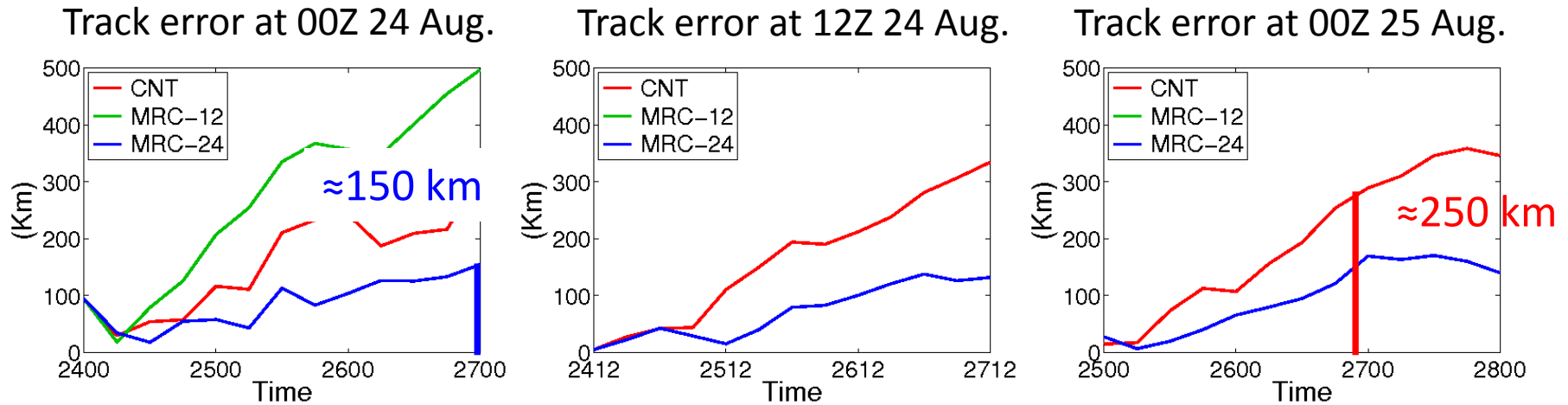


Initialized at 00Z 25 Aug.





# Track error of cold-started EPS



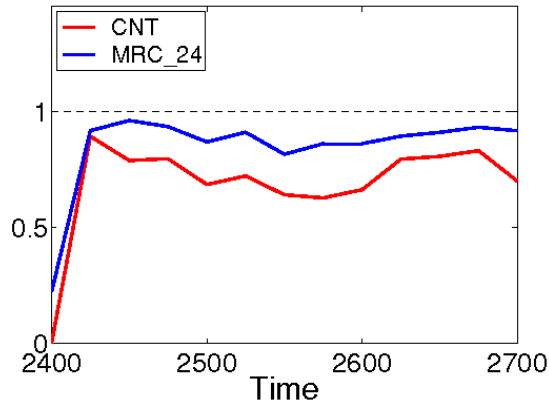
## Proper adjustment on ensemble can significantly improve the forecast skill

- It is expected that MRC\_24 outperforms CNT since it contains **next 24-h future information**.
- However, comparing **MRC\_24** initialized at **00Z 24** and **CNT** initialized at **00Z 25**, MRC shows better forecast skill than CNT when the **observation information is comparable**.

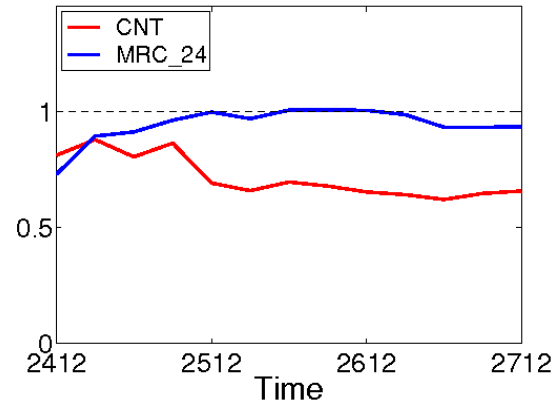
# Ensemble spread of cold-started EPS

- For an ideal EPS, the spread of the ensemble can well present the state uncertainty and the ratio of **spread (SPRD)** and **root mean square error (RMSE)** is close to **one**.

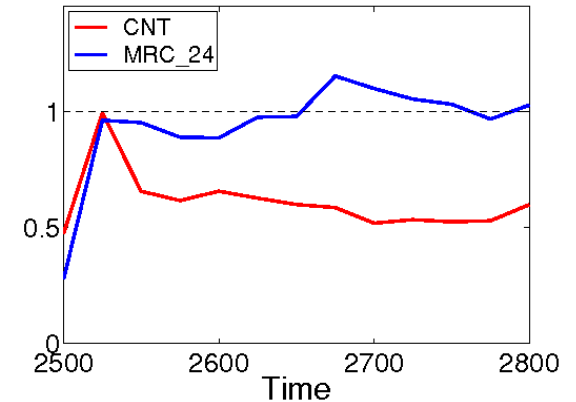
Ratio at 00Z 24 Aug.



Ratio at 12Z 24 Aug.



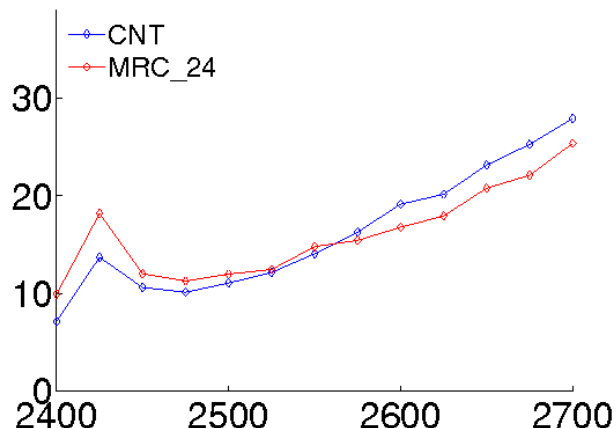
Ratio at 00Z 25 Aug.



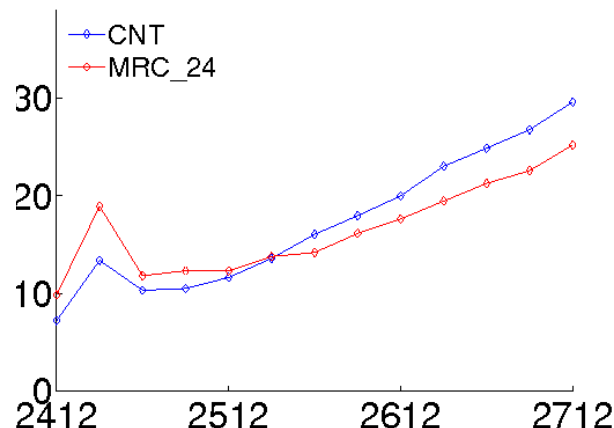
# Improvement for synoptic scale

- To emphasize the TC environment, the synoptic RMSE calculation **excludes the TC area**.

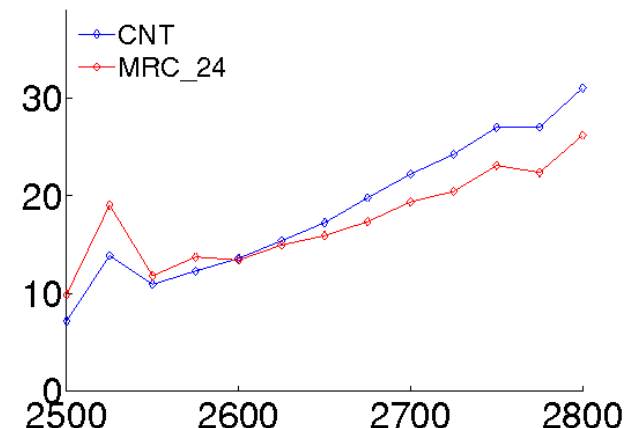
GeoP RMSE at 00Z 24 Aug.



GeoP RMSE at 12Z 24 Aug.



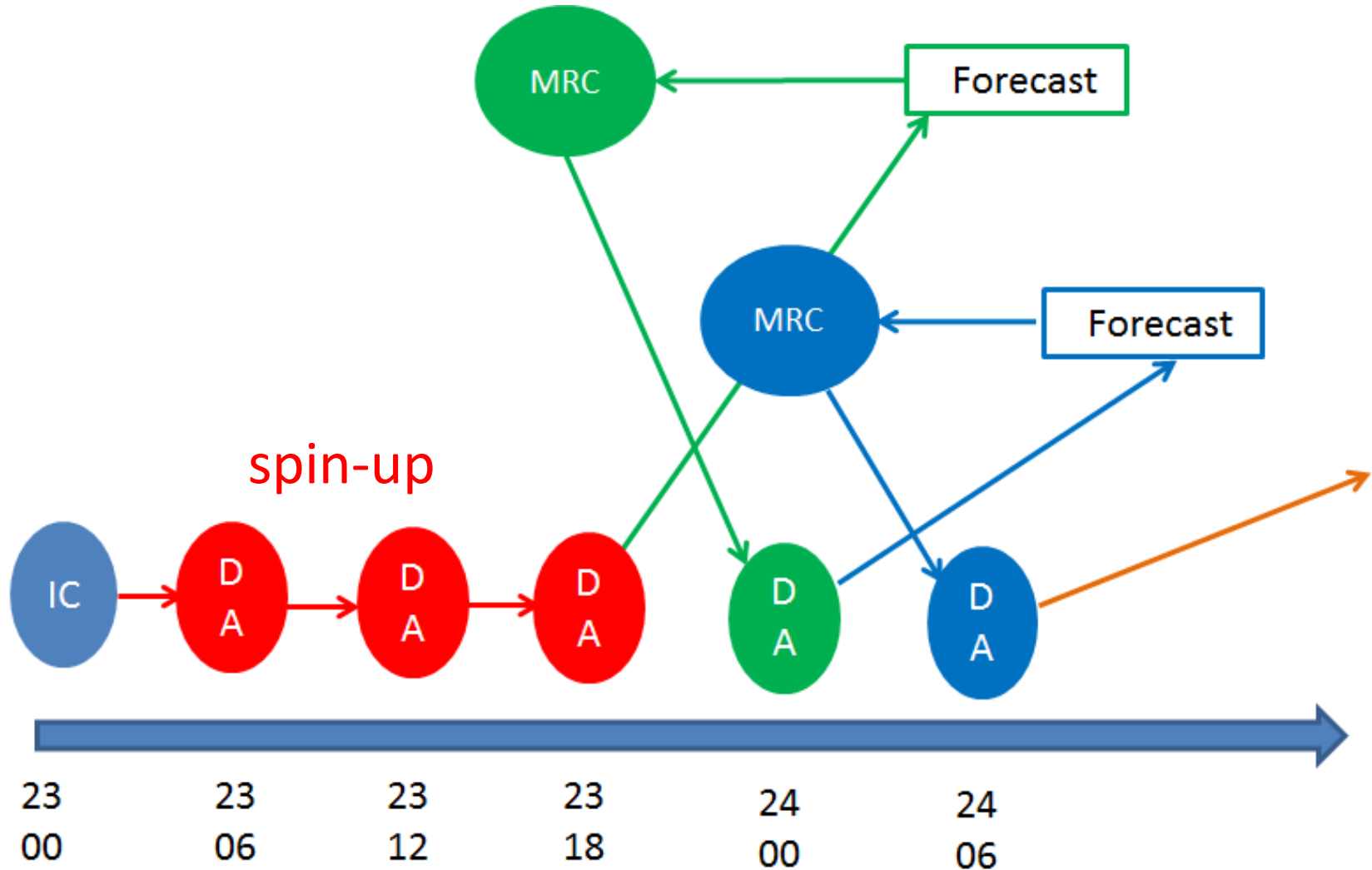
GeoP RMSE at 00Z 25 Aug.



- Although MRC uses **track error** to determine the best member, the positive impact can be found in the **synoptic scale features at longer leadtime**.

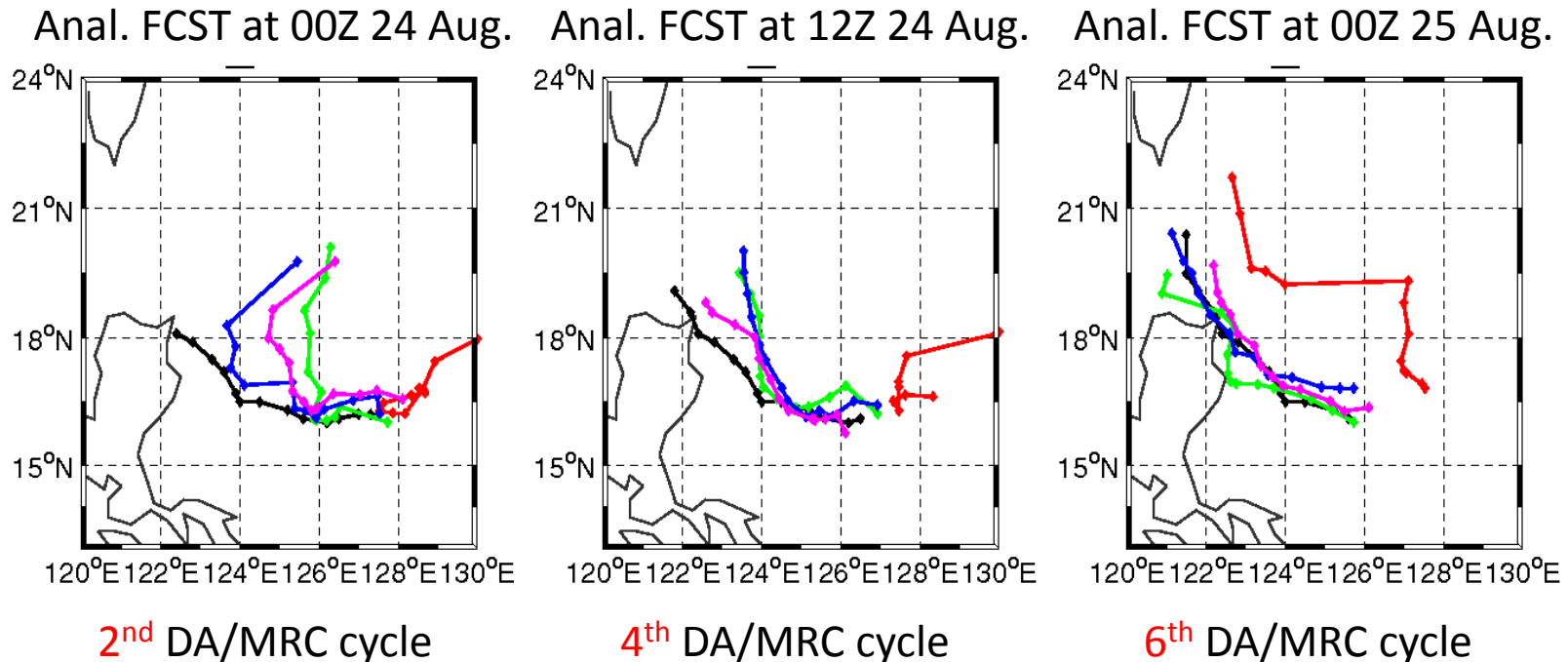
# WRF-LETKF (Warm-started EPS)

## Flow chart of MRC cycle



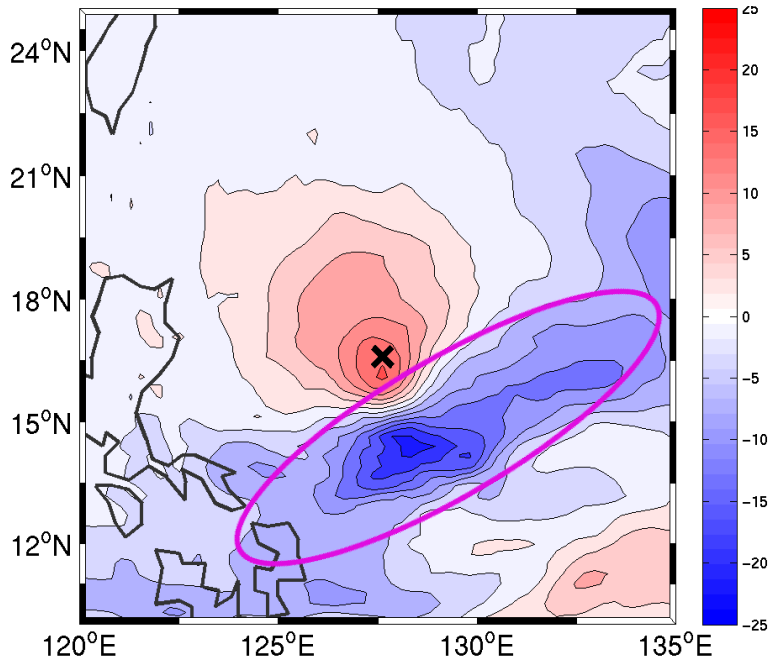
# WRF-LETKF (Warm-started EPS)

- CWB best track
- DA\_CNT: regular Data assimilation cycle
- MRC\_DA24a: One best member with smallest track error.
- MRC\_DA24b: Use average of the best five members as best member.
- MRC\_DA24c: Use average of the best group derived by cluster analysis.

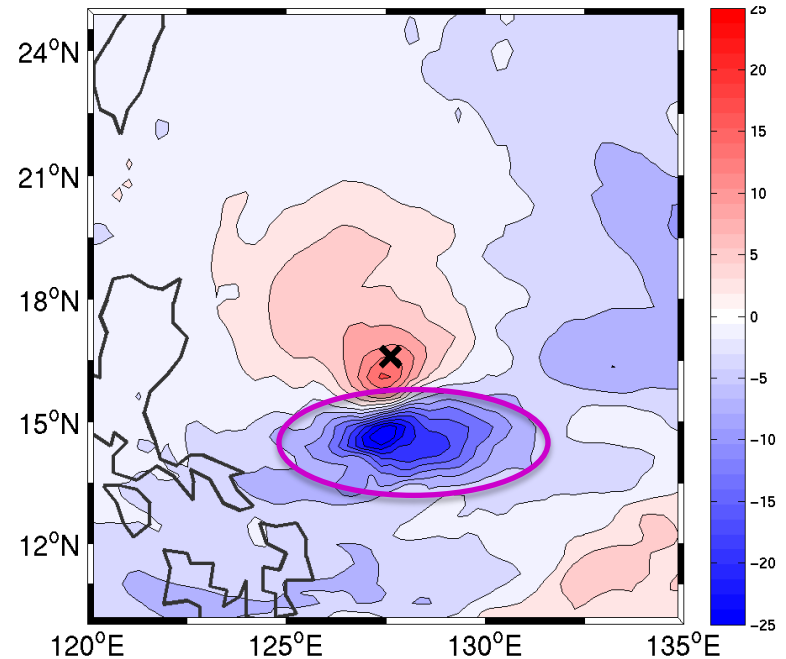


# Error covariance structure

Error covariance **W/O** MRC



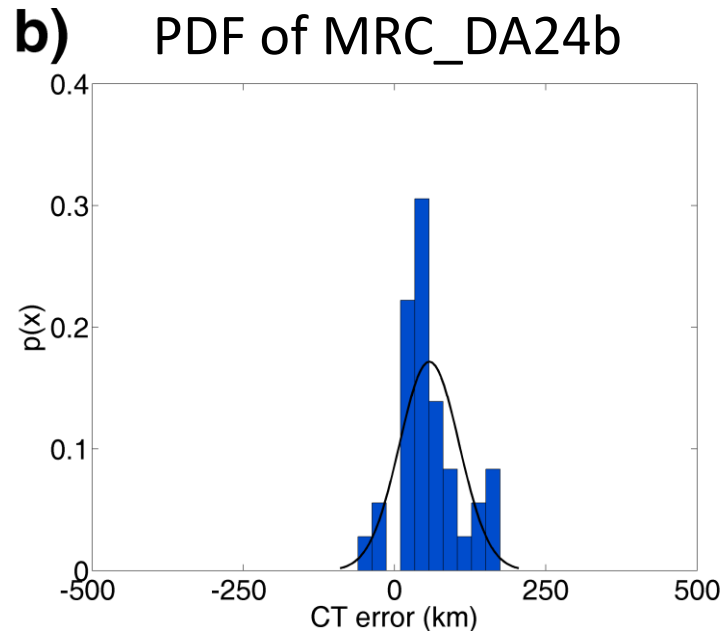
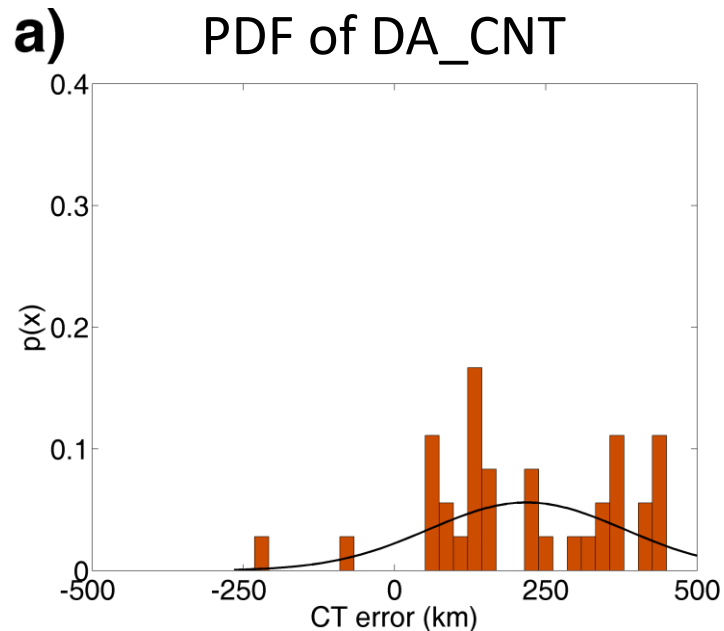
Error covariance **W/** MRC



- Without MRC, the negative covariance structure is very **board** and **link to another TC, Talas**.
- With MRC, the covariance structure is **more symmetric**.

# Gaussianity

- The Probability distribution of TC **cross track error** at 00Z 08/24 is used to emphasize the errors associated **with the moving direction**.
- The PDF of **MRC\_DA24b** fits the **normal distribution** with **95%** confidence level by  $\chi^2$  test. **But DA\_CNT does not.**



# Summary

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- For typhoon track prediction, we propose **the MRC method** to improve the poor ensemble forecast, which suffers from strong uncertainties and **non-Gaussian distribution**.
- In **cold-started EPS** experiment, we prove that the MRC is able to improve the TC track forecast.
- **In warm-started EPS**, with the **flow-dependent** characteristic of EnKF, the positive impact from the MRC can **feedback to the DA system**, further improving the background error covariance and analysis accuracy.
- A critical factor for MRC method to have positive impact is the metric for **deriving the best member**.
  - Results suggest that instead of **single member**, a better strategy is to define the best initial state with the **average of several good members**.
- Although MRC requires **future information** to determine the best member, for operational purpose, this could be an **valuable trade off** to adjust the ensemble at the **early TC developing stage**.



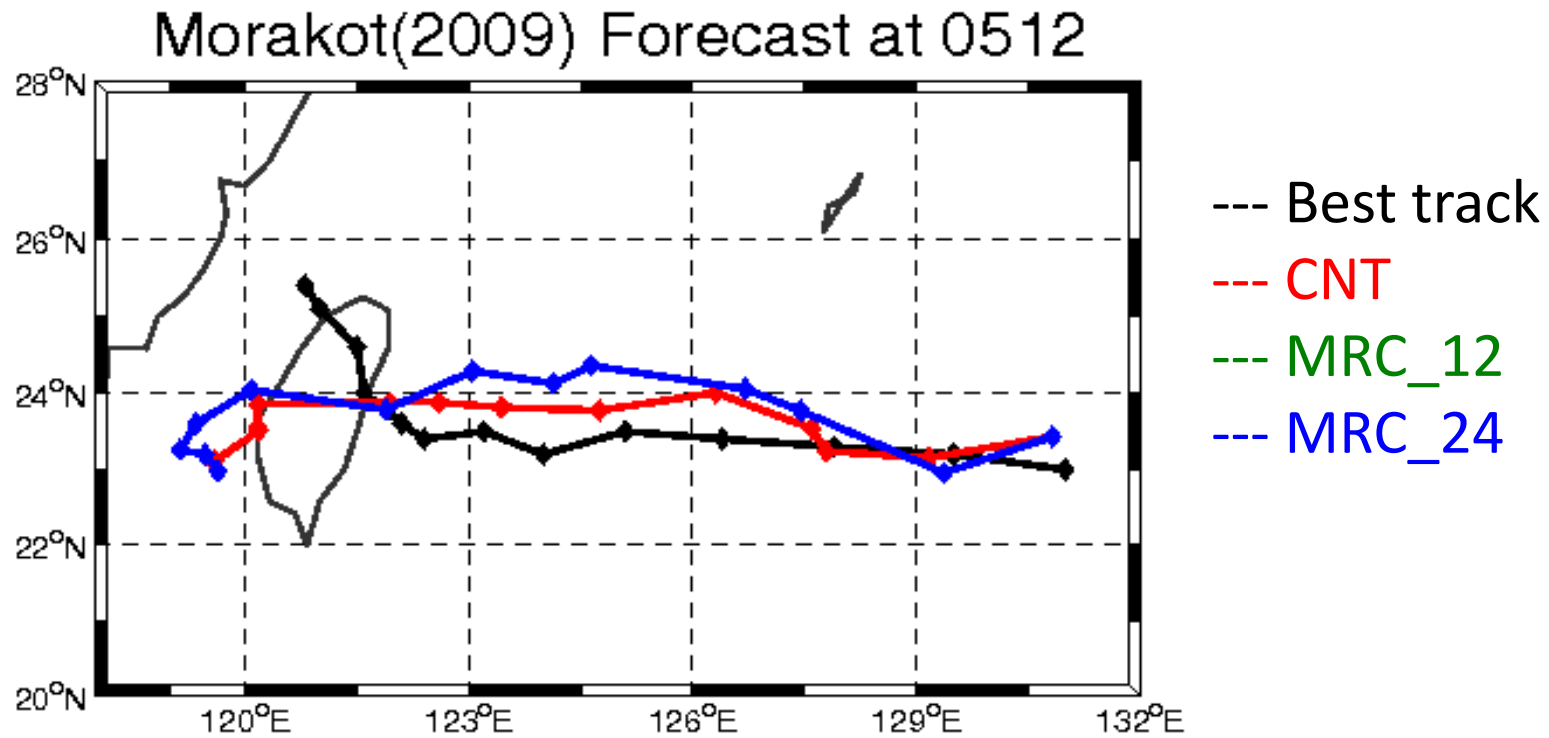
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Thanks for listening



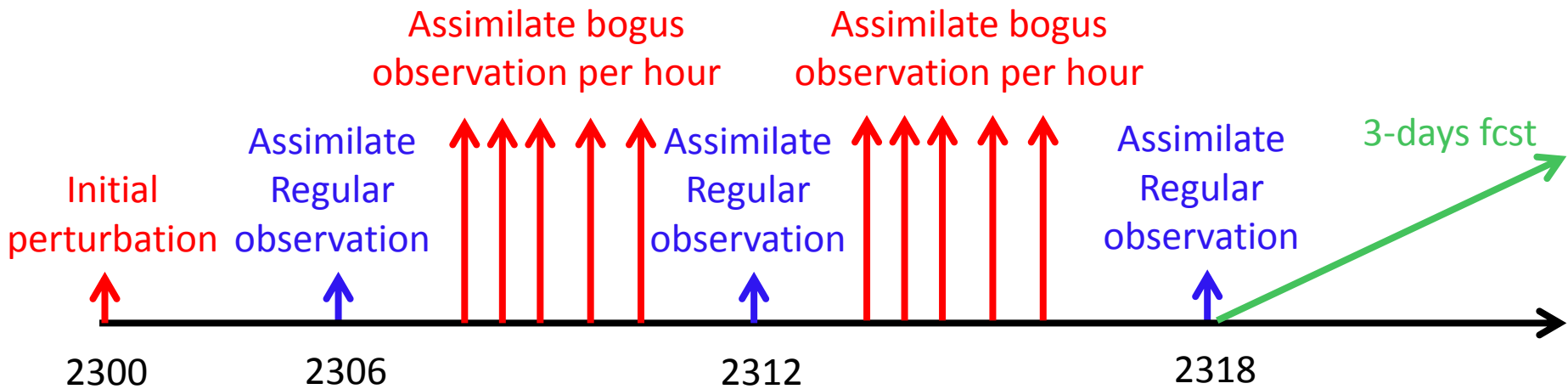
# Cold-started EPS for Morakot (2009)

- For **normal track forecast**, the MRC still has positive improvement.



# Bogus Data Assimilation

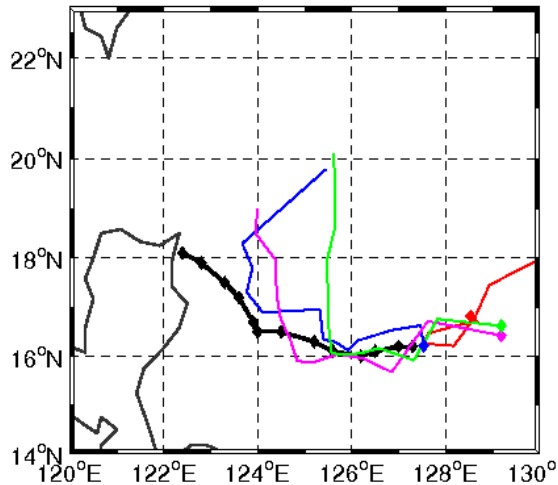
- **Initial position** and **initial intensity errors** are important sources of TC track forecast errors.
- Bogus assimilation (**BDA**) is used to improve the TC track forecast.



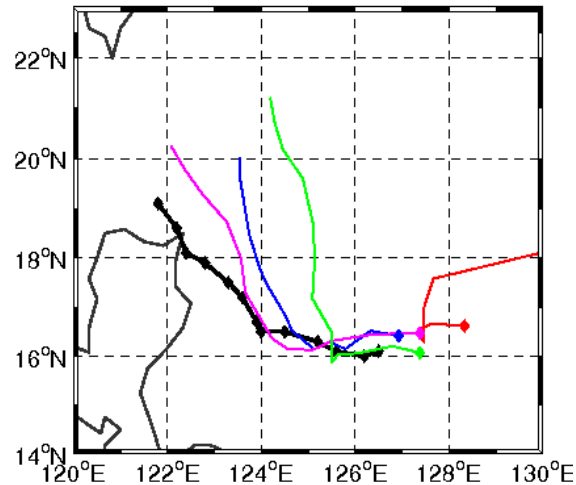
# BDA

- CWB best track
- **DA\_CNT: Assimilates regular observation.**
- **BDA\_CNT: Assimilate both regular and Bogus observations.**
- **MRC\_DA24b: Use the average of first five members as best member.**
- **MRC\_BDA24b: Same as MRC\_DA24b, but bogus data are assimilated during spin-up period.**

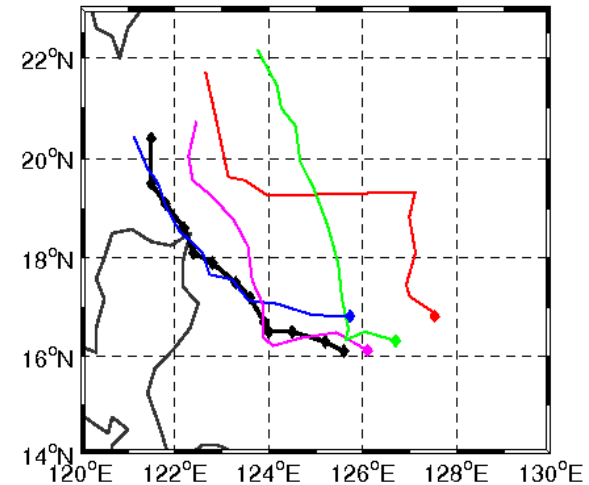
2400\_Forecast



2412\_Forecast

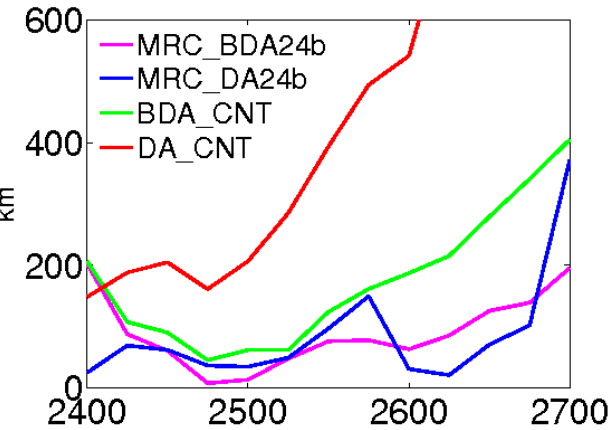


2500\_Forecast

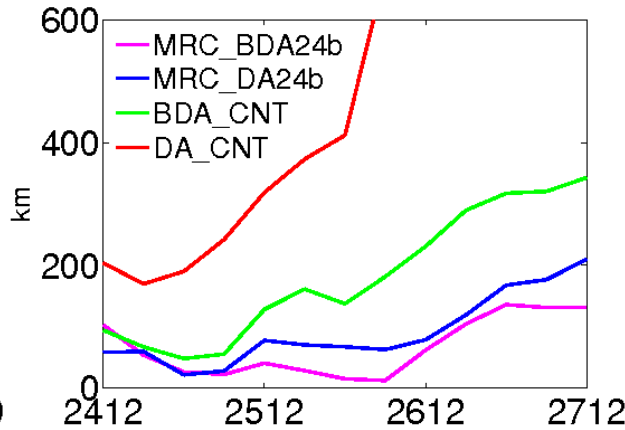


# BDA

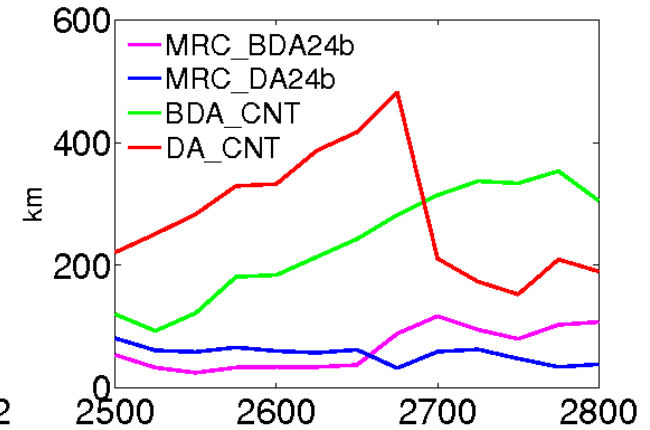
2400 Track Error



2412 Track Error



2500 Track Error



- The **initial position** has **no significant improvement** with BDA.
- However, since **TC structure is stronger**, the interaction of stronger TC circulation and the environment flow has a positive improvement for the track prediction