Satellite data assimilation for tropical weather prediction: Observing system design and observation impact

Yue (Michael) Ying and Fuqing Zhang Group meeting, Dec 11, 2015

Motivation

How to use satellite-based observations *optimally* to constrain model

- Temperature, moisture
- Wind
- Hydrometeors

Satellite-base observations:

- Direct observations of brightness temperature
- Retrieved temperature moisture profiles
- Cloud-tracing wind
- Surface-roughness wind

Data assimilation should consider:

- Observation availability, density (localization)
- Error modeling (inflation)
- QC, bias correction
- Nonlinearity in forward model (CRTM)
- Non-Gaussian variables (hydrometeors)

Observing system simulation experiment (OSSE)

Experimental design: EnKF OSSE



Truth: ERA-initialized WRF simulation

60-member EnKF First-guess from GFS Assimilate every 3 h

Advanced Baseline Imager (**ABI**) Channel-8 Brightness Temperature *Horizontal resolution: every pixel*

Advanced TIROS Operational Vertical Sounder (**ATOVS**): temperature, moisture profiles *Horizontal resolution: every 90 km*

Atmospheric Motion Vectors (AMV)

Localization (60 km for hydrometeors, 400 km for other variables)

ABI: Observation error inflation (use innovation as predictor)

The truth and no-DA case

Ch-14 Tb for verification





Deterministic forecast from prior ensemble mean

A "smoothed-out" prior mean (members all have different cloud cluster locations)

Smoothed clouds dissipated

Correct LBC forces out some convective clouds

Ch-14 Tb for verification

2011-10-13 00:00

Truth



ABI (prior)



ABI (posterior)



ABI observation recovers the spatial pattern of cloud clusters

ATOVS doesn't bring too much adjustment to the cloud field ATOVS (prior)





Ch-14 Tb for verification

2011-10-13 03:00

Truth



ABI (prior)



ABI (posterior)



ABI observation recovers the spatial pattern of cloud clusters

ATOVS doesn't bring too much adjustment to the cloud field ATOVS (prior)





Ch-14 Tb for verification

2011-10-13 06:00

Truth



ABI (prior)



ABI (posterior)



ABI observation recovers ATOVS the spatial pattern of cloud

ATOVS doesn't bring too much adjustment to the

clusters

cloud field

ATOVS (prior)





Ch-14 Tb for verification

2011-10-13 09:00

Truth



ABI (prior)



ABI (posterior)



ABI observation recovers the spatial pattern of cloud clusters

ATOVS doesn't bring too much adjustment to the cloud field ATOVS (prior)





Ch-14 Tb for verification

2011-10-13 12:00

Truth



ABI (prior)



ABI (posterior)



ABI observation recovers the spatial pattern of cloud clusters

ATOVS doesn't bring too much adjustment to the cloud field ATOVS (prior)





Analysis RMSE of ch-14 Tb



no-DA: doing a good job with clear region ATOVS: "smoothed-out" cloud contaminates clear region

ABI: prior also has smoothed cloud, assimilating Tb gets rid of them in posterior.

Analysis RMSE of wind, temperature and moisture

Time series



Both ABI and ATOVS reduces wind error gradually! ATOVS reduces more temperature/moisture error (directly observed) Adding AMV further reduces wind error

Analysis RMSE of wind, temperature and moisture

Vertical distribution



ATOVS reduces more temperature/moisture error (directly observed) Adding AMV further reduces wind error

Concluding remarks

- Proof-of-concept: Infrared brightness temperature observations are useful in constraining model cloud fields, and has positive impact on all other variables.
- Retrieved ATOVS profiles can improve T/Qv, but does not adjust cloud as much.

On going:

- The fast spreading ensemble cloud clusters suggest potential improvement when using higher frequency observations.
- Use Meteosat 7 (first generation) instead of ABI
- Consider using surface wind observations (CYGNSS, roughness-based wind speed) to further constrain wind field.

Supplementary slides Analysis RMSE of Hydrometeors



Supplementary slides Updates to hydrometeors



Supplementary slides Sensitivity of CRTM to hydrometeors

Control



No Q level25 up



1/10 all Q



More sensitive to location of cloud than cloud amount?

Supplementary slides Nonlinearity in forward operator (CRTM)

mean(Hx)





