

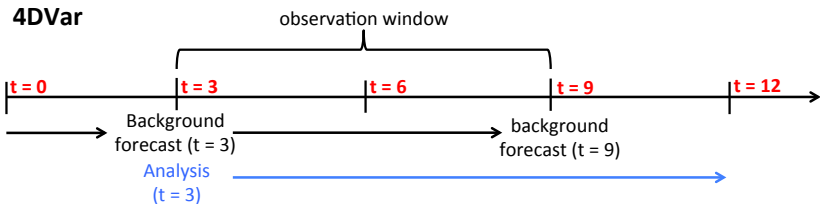
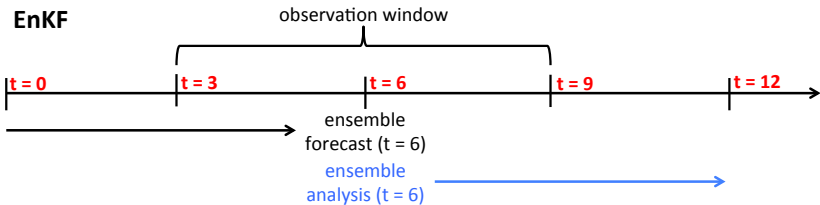
# A comparison of EnKF, 4DVar and E4DVar for a case of tropical cyclogenesis: more than just forecast results

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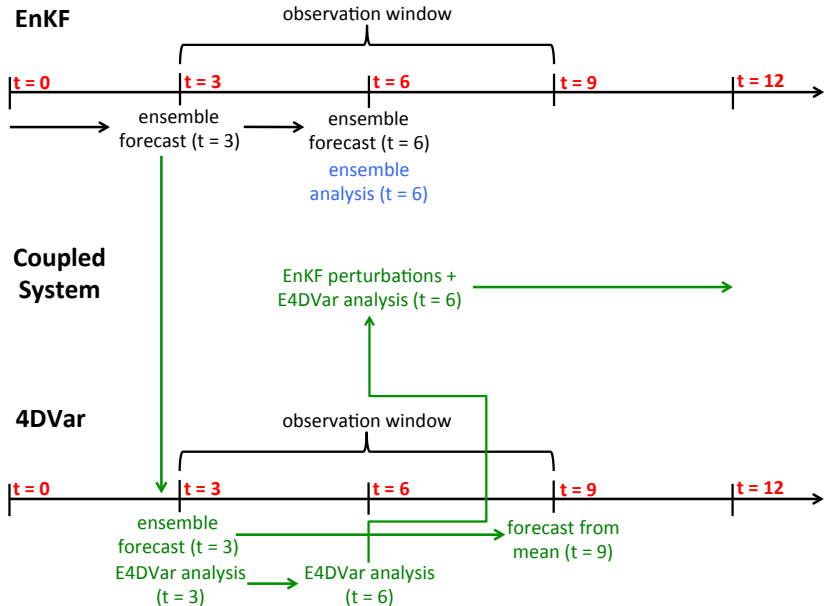
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# Coupling EnKF and 4DVar



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To find the analysis at time  $t$  ( $\mathbf{x}_t^a$ ), the standard 4DVar method seeks an increment ( $\delta\mathbf{x}_t$ ) from a background state ( $\mathbf{x}_t^b$ )

$$\mathbf{x}_t^a = \mathbf{x}_t^b + \delta\mathbf{x}_t.$$

The  $\delta\mathbf{x}_t$  is found by minimizing the cost function

$$J(\delta\mathbf{x}_t) = J_b(\delta\mathbf{x}_t) + J_o(\delta\mathbf{x}_t).$$

In E4DVar, the  $\delta \mathbf{x}_t$  is split into two parts

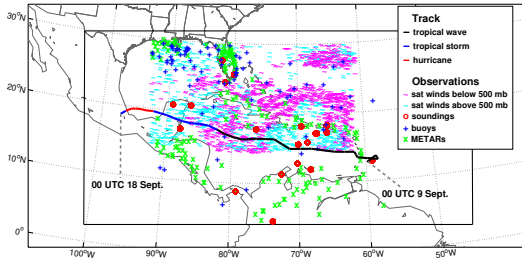
$$\delta \mathbf{x}_t = \delta \mathbf{x}_t^c + f(\alpha).$$

The cost function is then minimized with respect to two sets of control variables ( $\delta \mathbf{x}_t^c$  and  $\alpha$ )

$$J(\delta \mathbf{x}_t^c, \alpha) = \beta_1 J_b(\delta \mathbf{x}_t^c) + \beta_2 J_e(\alpha) + J_o(\delta \mathbf{x}_t^c, \alpha),$$

*(Lorenc, Q. J. R. Meteorol. Soc, 2003)*

# Case study: Hurricane Karl (2010)



Hurricane Karl (2010) developed from a broad low-pressure system that initiated near the northern coast of South America on 8 Sept., and became a tropical depression on 18 UTC 14 Sept.

- Pre-genesis Karl was targeted during the Predepression Investigation of Cloud Systems in the Tropics (PREDICT) field campaign.
- This study uses the WRF model to perform a set of cycling data assimilation experiments over the entire life cycle of Karl.

# Data assimilation configuration

## EnKF:

- 13.5-km horizontal grid spacing and 34 vertical levels
- 60 ensemble members
- 80% covariance relaxation to the prior
- 900 km radius of influence

# Data assimilation configuration

## 4DVar:

- Multi-incremental version with 13.5-km grid spacing outer loops and 40.5-km grid spacing inner loops
- WRF CV5 control variables
- Default length scales and amplitudes from month-long climatological covariance estimate

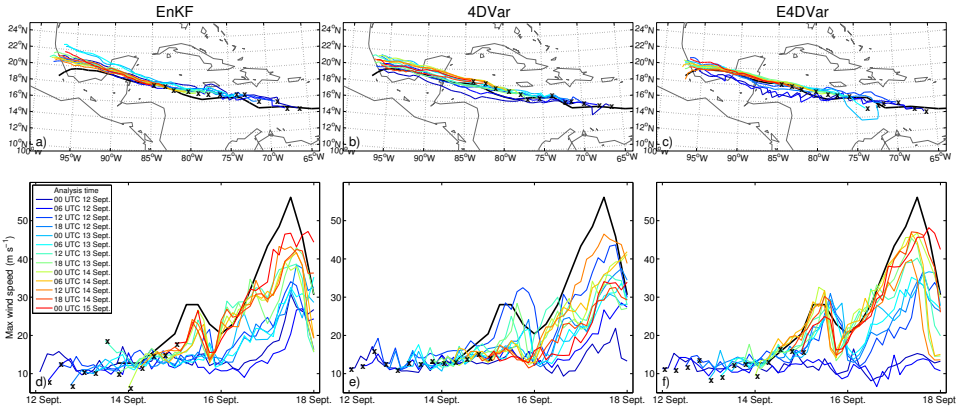


# Data assimilation configuration

## E4DVar:

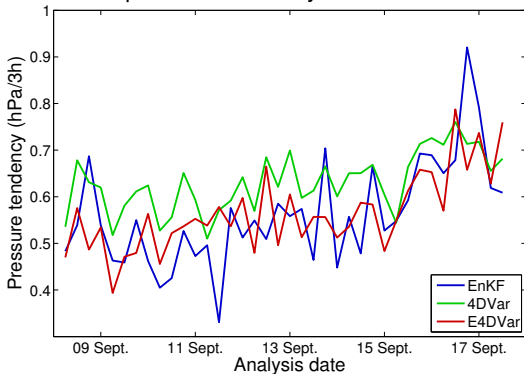
- EnKF component uses the previously mentioned setup
- The ensemble ( $\alpha$ ) control variables are preconditioned for localization using a 900-km radius of influence
- The hybrid analyses use 80% of the ensemble increment and 20% of the climatological increment

# Deterministic track and intensity forecasts



Forecasts are run from each analysis time to 00 UTC 18 Sept. using a 4.5-km nested domain.

3-h pressure tendency after initialization



- Domain-averaged dry surface pressure tendency is used to quantify imbalance following each data assimilation cycle.
- Pressure tendencies in the E4DVar simulations are comparable to EnKF, both of which perform better than 4DVar.
- The E4DVar system appears to be the most stable, with fewer spikes in pressure tendency.

- Solutions to 4DVar and E4DVar are found by searching down gradient of the cost function (e.g., conjugate gradient method).
- These methods require many iterations to adjust the control variables using information from the gradient of  $J$ .
- Each iteration requires the integration of the tangent linear and adjoint model (can be very expensive).

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Inner-loop iterations are averaged over the 40 cycles:

	4DVar	E4DVar
Mean iterations	37.5	25.6



# Conclusions

- An E4DVar data assimilation system outperformed the standalone methods for a case of tropical cyclogenesis.
- Coupling EnKF with 4DVar improves the initial condition balance over multi-incremental 4DVar.
- The use of ensemble information in 4DVar speeds the minimization of the cost function.
- Introducing ensemble perturbations into the 4DVar cost function can yield analysis increments that are far different from EnKF and 4DVar.